



Article Current-Mode Shadow Filter with Single-Input Multiple-Output Using Current-Controlled Current Conveyors with Controlled Current Gain

Montree Kumngern ¹, Fabian Khateb ^{2,3,4,*}, Tomasz Kulej ⁵, Martin Kyselak ⁴, Somkiat Lerkvaranyu ¹ and Boonying Knobnob ⁶

- ¹ Department of Telecommunications Engineering, School of Engineering, King Mongkut's Institute of Technology Ladkrabang, Bangkok 10520, Thailand; montree.ku@kmitl.ac.th (M.K.); somkiat.le@kmitl.ac.th (S.L.)
- ² Department of Microelectronics, Brno University of Technology, Technická 10, 601 90 Brno, Czech Republic
- ³ Faculty of Biomedical Engineering, Czech Technical University in Prague, Nám. Sítná 3105, 272 01 Kladno, Czech Republic
- ⁴ Department of Electrical Engineering, Brno University of Defence, Kounicova 65, 662 10 Brno, Czech Republic; martin.kyselak@unob.cz
- ⁵ Department of Electrical Engineering, Czestochowa University of Technology, 42-201 Czestochowa, Poland; kulej@el.pcz.czest.pl
- ⁶ Faculty of Engineering, Rajamangala University of Technology Thanyaburi, Pathum Thani 12110, Thailand; kboonying@rmutt.ac.th
- Correspondence: khateb@vutbr.cz

Abstract: In this paper, a novel current-mode shadow filter employing current-controlled current conveyors (CCCIIs) with controlled current gains is presented. The CCCII-based current-mode shadow filters are resistorless and can offer a number of advantages such as circuit simplicity and electronic tuning capability. The proposed shadow filters offer five filtering functions, i.e., low-pass, high-pass, band-pass, band-stop, and all-pass functions, in the same topology. Furthermore, no component matching condition is required to realize all the transfer functions. The natural frequency and quality factor adjustment is possible by using the CCCII current gains without the need to use external amplifiers, all capacitors are grounded, and the filter terminals offer low-input and high-output impedance. To verify the functionality and feasibility of the new topologies, the proposed circuits were simulated using SPICE and the transistor model process parameters NR100N (NPN) and PR100N (PNP) from AT&T's bipolar arrays ALA400-CBIC-R. The simulation results are consistent with the theory. The CCCII experimental setup was designed using commercially available 2N3904 (NPN) and 2N3906 (PNP) transistors with a supply voltage of ± 2.5 V. The measurement results confirm the performance of the designed filters.

Keywords: shadow filter; current-mode filter; current-controlled current conveyor; second-generation current conveyor

1. Introduction

Over the last decade, second-generation current conveyors (CCIIs) have been used to realize current-mode analog circuits. This is because CCII-based circuits offer better signal bandwidth, higher linearity, circuit simplicity, and wider dynamic range performances compared with the operational amplifiers (op-amps)-based circuits [1,2]. In addition, a CCII is simpler to implement compared to the op-amp structure.

Usually, a conventional CCII has three terminals (x-, y-, and z-terminal) [3]. Its electrical symbol is shown in Figure 1, while its terminal characteristics in ideal case are given by Equation (1).



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$$\begin{pmatrix} I_y \\ V_x \\ I_z \end{pmatrix} = \begin{pmatrix} 0 & 0 & 0 \\ 1 & 0 & 0 \\ 0 & 1 & 0 \end{pmatrix} \begin{pmatrix} V_y \\ I_x \\ V_z \end{pmatrix}$$
(1)



Figure 1. Electrical symbol of CCII.

It can be noted that the y-terminal is a voltage input that has a high impedance level (ideally infinity), the x-terminal is a voltage signal output and also a current signal input, with low impedance level (ideally zero), and the z-terminal is a current output with a high impedance level (ideally infinity). In practice, the parasitic resistance at the x-terminal (R_x) of the CCII can be controlled by its bias current, which can be used as a design parameter. Such a device is called a current-controlled current conveyor (CCCII) [4]. Circuits based on CCCII can thus reduce the number of passive resistors and offer the possibility of electronic control.

It should be noted that in the ideal case is $V_x = V_y$ for CCII and $V_x = I_x R_x + V_y$ for CCCII, while $I_z = I_x$ for both circuits. Note that the voltage and current gain in these formulas is equal to one. To increase the functionality, the CCCII with controlled current gain has also been proposed [5]. This device offers an adjustable current gain between the *z*- and x-terminals, which can be used as a design parameter for such applications as filters and oscillators. The CCII/CCCII can be realized using bipolar junction transistor (BJT) technology [5] or complementary metal oxide semiconductor (CMOS) technology [6,7]. In this work, a CCCII with controlled current gain is used to realize current-mode shadow filters.

The shadow filter was first introduced in [8]. The concept of the conventional shadow filter is to use an external amplifier to adjust the natural frequency and the quality factor of the second-order filters without changing the value of parameters such as capacitances and resistances of the original topology. However, the shadow filter in [8] does not provide independent control of the natural frequency and the quality factor. To obtain independent control of the above-mentioned parameters, the shadow filter was further developed, and two new systems were proposed [9]. The first system in [9] consists of a second-order filter and an amplifier. The LP and BP outputs are summed and amplified by the amplifier, and the output signal of the amplifier is summed with the input signal. Thus, the quality factor can be controlled by an external amplifier without changing the natural frequency. The second system in [9] was further developed by adding another amplifier to the first system. Thus, the second system in [9] consists of a second-order filter and two external amplifiers. The first amplifier is used to amplify the BP output, while the second one is used to amplify the LP output, and the output signals of the two amplifiers are summed with the input signal. Consequently, the quality factor can be modified by the first external amplifier, while the natural frequency can be modified by the second one. In this work, the two systems of shadow filters in [9] will be designed using CCCII with controlled current gain as active elements. It will be shown that the function of external amplifiers can be obtained using the current gains of CCCIIs.

Many shadow filters (also known as frequency-agile filters) have been introduced [10–34]. These filters can be used for various radio applications and sensor networks including environmental monitoring, vital signs monitoring, and military applications. Considering the operating mode of these filters, they can be divided into three operating modes: voltage-mode [10–22], current-mode [23–31], and mixed-mode (or multi-mode) [32–34].

Considering the active devices used to realize the voltage-mode shadow filters in [10-22], the circuit in [10] uses operational transresistance amplifiers (OTRA), the circuits in [11-13]

use current-feedback operational amplifiers (CFOA), the circuits in [14,16–18] use voltage differencing transconductance amplifiers (VDTA), the circuit in [15] uses voltage differencing differential difference amplifiers (VDDDA), the circuit in [19] uses voltage differencing gain amplifiers (VDGA), while the circuit in [21] uses operational transconductance amplifiers (OTA), and the circuits in [22] use differential difference transconductance amplifiers (DDTA). The shadow filters in [15–19,21,22] offer an electronic tuning capability, but only the filter in [15] offers five filtering functions, namely low-pass (LP), high-pass (HP), band-pass (BP), band-stop (BS), and all-pass (AP). However, the voltage-mode filter in [15] does not provide low-output impedance, which is required for voltage-mode circuits.

This work is focused on the current-mode shadow filter that offers low-input and high-output impedances, which is required for current-mode circuits. With respect to the current-mode shadow filters in [23–31], the circuits in [23–27] use current difference transconductance amplifier (CDTA), the circuit in [28] uses operational floating current conveyor (OFCC), the circuit in [29] uses current backwards trans-conductance amplifier (CBTA), while the circuit in [30] uses current controlled current differencing cascaded-transconductance amplifier (CC-CDCTA), and the circuit in [31] uses current conveyor cascaded transconductance amplifier (CCCTA). The shadow filters in [23–27,29–31] offer an electronic tuning capability, but only the shadow filter in [31] can offer low-pass, high-pass, band-pass, band-stop, and all-pass filtering functions in one system. The circuit in [31] employs one CCCTA, one EX-CCCTA, and two capacitors. Although the circuit is based on a small number of active blocks, the structure of active blocks is rather complex.

With respect to the mixed-mode shadow filters in [32–34], the circuit in [33,34] can realize low-pass, high-pass, band-pass, band-stop, and all-pass filtering functions in the same topology. However, when the mixed-mode circuit in [33] operates in current-mode, the input matching condition, namely $I_{in} = I_{in1} = I_{in2}$, is required. This means that the circuit requires additional circuits to produce multiple copies of a single input signal. The filter in [33] employs two FD-CCCTAs (fully differential current conveyor cascaded transconductance amplifier), three capacitors, and two MOS resistors, while the filter in [34] employs two DDCCCTAs (differential current conveyor cascaded transconductance amplifiers), two capacitors, and one MOS resistor. However, the active block structures used in these filters [34,35] suffer from a relatively high complexity.

This paper presents current-mode shadow filters using CCCIIs with controlled current gain as active elements. The circuits employ three CCCIIs and two grounded capacitors. This work shows that the current gains of the used CCCIIs can perform the role of external amplifiers to adjust the natural frequency and quality factor of the proposed universal filters without the need to modify their internal parameters. The proposed current-mode shadow filters offer low-pass, high-pass, band-pass, band-stop, and all-pass filtering functions in the same topology with low complexity. The natural frequency and the quality factor can be adjusted by the current gains of CCCIIs and can be electronically controlled. The proposed current-mode filters offer low-input and high-output impedances, which is desirable in current-mode circuits. The paper is organized as follows: Section 2 describes the structure of the CCCII with controlled current gain, the proposed current-mode shadow filters and the nonideality analysis. The simulation results of the CCCII with controlled current gain and the shadow filter are shown in Section 3. Section 4 presents the experimental results of the proposed filters and Section 5 concludes the paper.

2. Proposed Circuit

2.1. CCCII with Controlled Current Gain

The electrical symbol of the CCCII with controlled current gain and multiple current outputs is shown in Figure 2. In the ideal case, this element can be described by the following matrix equation:

$$\begin{pmatrix} I_y \\ V_x \\ I_{z\pm} \\ I_{kz\pm} \end{pmatrix} = \begin{pmatrix} 0 & 0 & 0 & 0 \\ 1 & R_x & 0 & 0 \\ 0 & \pm 1 & 0 & 0 \\ 0 & \pm k & 0 & 0 \end{pmatrix} \begin{pmatrix} V_y \\ I_x \\ V_{z\pm} \\ V_{kz\pm} \end{pmatrix}$$
(2)



The CCCII with controlled current gain can be implemented using both BJT [5–7] as well as CMOS [6,7] technologies. This paper proposes a simple BJT implementation shown in Figure 3. The main circuit consists of the translinear loop (Q_1 - Q_4) and the positive and negative current mirrors with adjustable gain (Q_{22} - Q_{25} , Q_{26} - Q_{29}). Assume that transistors Q_1 to Q_4 of a translinear loop are identical and are biased by the current I_{set} . The parasitic resistance at x-terminal is given by [4]:

$$R_x = \frac{V_T}{2I_{set}} \tag{3}$$

where V_T is the thermal voltage (~26 mV at 27 °C) and I_{set} is the bias current. Note that R_x can be controlled by I_{set} .



Figure 3. BJT implementation of the CCCII with controlled current gain.

Assuming further that transistors Q_{22} to Q_{25} of positive current mirrors and transistors Q_{26} to Q_{29} of the negative current mirrors are identical, the current gain *k* of the CCCII in Figure 3 is given by [5]:

$$k = \frac{I_a}{I_b} \tag{4}$$

It should be noted that the current gain k can be linearly controlled. Moreover, it is independent of temperature variation.

2.2. Proposed Current-Mode Shadow Filter

Figure 4a shows the block diagram of the current-mode shadow filter, which consists of a second-order filter (2nd-order filter) that provides three filtering functions i.e., LP, HP, and BP filters, and the amplifier (A) [9]. The outputs of the LP and HP filters are further summed and amplified by the amplifier A, and the output signal of the amplifier is then

summed with the input signal. Figure 4b shows the first proposed current-mode shadow filter based on the translinear current conveyors (CCCIIs) with controlled current gains, which is realized based on the block diagram in Figure 4a. The CCCII₁ to CCCII₃, C₁, and C₂ form a second-order filter that provides three outputs of, LP, HP, and BP filters. This is based on two integrator loops, of which CCCII₁ and C₁ create the first integrator, and CCCII₂, and C₂ create the second. The current gains of CCCII₂ (k_2) and CCCII₃ (k_3) act as an external amplifier (i.e., $k_2 = k_3 = k = A$). The outputs of the LP and HP filters are amplified by k_2 and k_3 , respectively, and are next fed to the input node of the filter. Thanks to the multiple-output CCCII, the BS filter (I_{BS}) can be obtained by summing the outputs of the LP and HP filters.



Figure 4. First current-mode shadow filter: (**a**) block diagram, (**b**) first proposed current-mode shadow filter using CCCIIs.

It should be noted that the input current I_{in} is applied to the x-terminal of CCCII which provides a low impedance level, while the output currents I_{LP} , I_{HP} , I_{BP} , and I_{BS} are supplied from the z-terminals of the CCCII which provides a high impedance level. The circuit uses two grounded capacitors and no passive resistors, which reduces the chip area when it is realized in integrated form.

Using nodal analysis and (2), the output currents of the LP (I_{LP}), HP (I_{HP}), BP (I_{BP}), and BS (I_{BS}) filters in Figure 4b can be respectively expressed as

$$I_{LP} = \frac{1}{s^2 C_1 C_2 R_{x1} R_{x2} (1+k_3) + s C_2 R_{x2} + (1+k_2)} I_{in}$$
(5)

$$I_{HP} = \frac{s^2 C_1 C_2 R_{x1} R_{x2}}{s^2 C_1 C_2 R_{x1} R_{x2} (1+k_3) + s C_2 R_{x2} + (1+k_2)} I_{in}$$
(6)

$$I_{BP} = -\frac{sC_2R_{x2}}{s^2C_1C_2R_{x1}R_{x2}(1+k_3) + sC_2R_{x2} + (1+k_2)}I_{in}$$
(7)

$$I_{BS} = \frac{s^2 C_1 C_2 R_{x1} R_{x2} + 1}{s^2 C_1 C_2 R_{x1} R_{x2} (1 + k_3) + s C_2 R_{x2} + (1 + k_2)} I_{in}$$
(8)

By combining the currents I_{BP} and I_{BS} , the output current of the AP filter (I_{AP}) can be obtained as

$$I_{AP} = \frac{s^2 C_1 C_2 R_{x1} R_{x2} - s C_2 R_{x2} + 1}{s^2 C_1 C_2 R_{x1} R_{x2} (1+k_3) + s C_2 R_{x2} + (1+k_2)} I_{in}$$
(9)

where R_{x1} and R_{x2} are, respectively, the parasitic resistances of CCCII₁ and CCCII₂, while k_2 and k_3 are, respectively, the current gains of CCCII₂ and CCCII₃.

Assuming $k_2 = k_3 = k$ (k = A), the natural frequency (ω_o) and the quality factor (Q) can be respectively given by

$$\omega_o = \frac{1}{\sqrt{C_1 C_2 R_{x1} R_{x2}}} \tag{10}$$

$$Q = (1+k)\sqrt{\frac{C_1 R_{x1}}{C_2 R_{x2}}}$$
(11)

It should be noted that the parameter ω_o can be electronically controlled by R_{x1} and R_{x2} via I_{set1} and I_{set2} (i.e., $I_{set1} = I_{set2}$) and the parameter Q can be electronically controlled via k ($k = k_2 = k_3$).

From (5), (6), (8), and (9), it can be seen that when the parameter Q is varied by k, the passband gains of the LP, HP, BS, and AP filters change. Namely, increasing the Q value will decrease the passband gains of these filters, except the passband gain of the BP filter, which will be constant.

It should be noted that the shadow filter in Figure 4 uses one external amplifier to modify only the quality factor. Figure 5a shows the block diagram for the second current-mode shadow filter which consists of a 2nd order filter and two amplifiers (A_1 and A_2) [9]. The output signals BP and LP are amplified, respectively, by A_1 and A_2 , and summed with the input signal. Thus, the quality factor and the natural frequency can be independently controlled using the amplifiers A_1 and A_2 .



Figure 5. Second current-mode shadow filter: (**a**) block diagram, (**b**) second proposed current-mode shadow filter using CCCIIs.

Figure 5b shows the proposed second realization of the current-mode shadow filter using CCCIIs with controlled current gains, which realizes the block diagram in Figure 5a. The CCCII₁ to CCCII₃, C₁, and C₂ form a second-order filter that provides three outputs of the LP, HP, and BP filters, which are similar to the ones in Figure 4b. Compared with Figure 5a, the gain A₁ is realized by k₁ of CCCII₁ and A₂ is realized by k₂ of CCCII₂. The output of the BP filter is amplified by k₁ and the output of the LP filter is amplified by k₂. The amplified output signals of the BP and LP filters are applied to the input node of the filter.

Using nodal analysis and (2), the output currents of the LP (I_{LP}), HP (I_{HP}), BP (I_{BP}), and BS (I_{BS}) filters of Figure 5b can be respectively expressed as

$$I_{LP} = \frac{1}{s^2 C_1 C_2 R_{x1} R_{x2} + s C_2 R_{x2} (1 - k_1) + (1 - k_2)} I_{in}$$
(12)

$$I_{HP} = \frac{s^2 C_1 C_2 R_{x1} R_{x2}}{s^2 C_1 C_2 R_{x1} R_{x2} + s C_2 R_{x2} (1 - k_1) + (1 - k_2)} I_{in}$$
(13)

$$I_{BP} = -\frac{sC_2R_{x2}}{s^2C_1C_2R_{x1}R_{x2} + sC_2R_{x2}(1-k_1) + (1-k_2)}I_{in}$$
(14)

From I_{LP} and I_{HP} , the output current of the BS filter (I_{BS}) can be obtained as

$$I_{BS} = \frac{s^2 C_1 C_2 R_{x1} R_{x2} + 1}{s^2 C_1 C_2 R_{x1} R_{x2} + s C_2 R_{x2} (1 - k_1) + (1 - k_2)} I_{in}$$
(15)

From $I_{LP}I_{HP}$, and I_{BP} , the output current of the AP filter (I_{AP}) can be obtained as

$$I_{AP} = \frac{s^2 C_1 C_2 R_{x1} R_{x2} - s C_2 R_{x2} + 1}{s^2 C_1 C_2 R_{x1} R_{x2} + s C_2 R_{x2} (1 - k_1) + (1 - k_2)} I_{in}$$
(16)

The natural frequency (ω_o) and the quality factor (*Q*) of the filters are given by

$$\omega_o = \sqrt{\frac{1 - k_2}{C_1 C_2 R_{x1} R_{x2}}} \tag{17}$$

$$Q = \frac{\sqrt{1 - k_2}}{1 - k_1} \sqrt{\frac{C_1 R_{x1}}{C_2 R_{x2}}}$$
(18)

As can be seen, the parameter ω_0 can be controlled by k_2 (A_2) in the range of $0 < k_2 < 1$ and the parameter Q can be controlled by k_1 (A_1) in the range of $0 < k_1 < 1$. Thus, the parameters ω_0 and Q can be independently controlled. It could be noted that adjusting the parameter ω_0 by k_2 will affect the parameter Q. In order to provide constant value of the parameter Q, when the parameter ω_0 is varied by k_2 , k_1 must be used to adjust Q.

From (12), (14)–(16), it can be seen that varying the parameter ω_0 by k₂ will affect the passband gains of the LP, BP, BS, and AP filters. Namely, increasing k₂ will increase the passband gains of these filters, except the passband gain of the HP filter, which will be constant.

2.3. Impact of Non-Idealities

Taking into account the non-idealities of the CCCII with controlled current gain, its characteristics can be described by the following matrix equation

$$\begin{pmatrix} I_y \\ V_x \\ I_{z\pm} \\ I_{k\pm} \end{pmatrix} = \begin{pmatrix} 0 & 0 & 0 & 0 \\ \alpha & R_x & 0 & 0 \\ 0 & \pm \beta & 0 & 0 \\ 0 & \pm \beta_k k & 0 & 0 \end{pmatrix} \begin{pmatrix} V_y \\ I_x \\ V_{z\pm} \\ V_{k\pm} \end{pmatrix}$$
(19)

where $\alpha = 1 - \varepsilon_v$ (with $\varepsilon_v \ll 1$) denotes the voltage tracking error from y- to x-terminal, $\beta = 1 - \varepsilon_i (\varepsilon_i \ll 1)$ denotes the current tracking error from x- to z-terminals, $\beta_k = 1 - \varepsilon_{ik} (\varepsilon_{ik} \ll 1)$ denotes the current tracking error from x- to kz-terminals.

The CCCII symbol with non-idealities is shown in Figure 6, where the additional passive elements represent the parasitic resistances and capacitances associated with each terminal of the device. The x-terminal has a parasitic serial resistance R_x , the y-terminal has a high-value parasitic resistance R_y in parallel with a low-value parasitic capacitance C_y , the z-terminal has a high-value parasitic resistance R_z in parallel with a low-value parasitic capacitance C_z , and the kz-terminal has a high-value parasitic resistance R_{kz} in parallel with a low-value parasitic with a low-value parasitic capacitance C_{kz} .



Figure 6. Parasitic resistances and capacitances of CCCII.

Using (19) and nodal analysis, the denominator (D(s)) of the transfer functions of the filter in Figure 4b can be expressed by

$$D(s) = s^2 C_1 C_2 R_{x1} R_{x2} (1 + k_3 \beta_{k3}) + s C_2 R_{x2} \alpha_1 \beta_1 + (\alpha_1 \alpha_2 \beta_1 \beta_2 + k_2 \beta_{k2})$$
(20)

The parameters ω_0 and Q in (10) and (11) can be respectively rewritten as

$$\omega_o = \frac{1}{\sqrt{C_1 C_2 R_{x1} R_{x2}}} \sqrt{\frac{\alpha_1 \alpha_2 \beta_1 \beta_2 + k_2 \beta_{k2}}{1 + k_3 \beta_{k3}}}$$
(21)

$$Q = \frac{1 + k_3 \beta_{k3}}{\alpha_1 \beta_1} \sqrt{\frac{C_1 R_{x1}}{C_2 R_{x2}} \cdot \frac{\alpha_1 \alpha_2 \beta_1 \beta_2 + k_2 \beta_{k2}}{1 + k_3 \beta_{k3}}}$$
(22)

Using (19) and nodal analysis, the denominator (D(s)) of the transfer functions of the filter in Figure 5b can be expressed by

$$D(s) = s^{2}C_{1}C_{2}R_{x1}R_{x2} + sC_{2}R_{x2}(\alpha_{1}\beta_{1} - k_{1}\beta_{k1}) + (\alpha_{1}\alpha_{2}\beta_{1}\beta_{2} - k_{2}\alpha_{1}\beta_{1}\beta_{k2})$$
(23)

The parameters ω_o and Q in (17) and (18) can be respectively rewritten as

$$\omega_o = \sqrt{\frac{\alpha_1 \alpha_2 \beta_1 \beta_2 - k_2 \alpha_1 \beta_1 \beta_{k2}}{C_1 C_2 R_{x1} R_{x2}}}$$
(24)

$$Q = \frac{\sqrt{\alpha_1 \alpha_2 \beta_1 \beta_2 - k_2 \alpha_1 \beta_1 \beta_{k2}}}{\alpha_1 \beta_1 - k_1 \beta_{k1}} \sqrt{\frac{C_1 R_{x1}}{C_2 R_{x2}}}$$
(25)

where α_j is the voltage gain error, β_j , and β_{kj} are the current gain errors of *j*-th CCCII (*j* = 1, 2, 3).

From (24) and (25), it can be seen that the voltage gain errors and the current gain errors of CCCIIs will affect the natural frequency and the quality factor of the proposed shadow filters in Figures 4b and 5b. However, this impact can be compensated by electronic tuning.

Considering the proposed shadow filter in Figure 4b by including CCCII with the parasitic components in Figure 6, the denominator of all filtering functions is given by

$$D(s) = \{s^2 C_{T1} C_{T2} R_{x1} R_{x2} (1+k_3) + s C_{T2} R_{x2} \left(1 + \frac{C_{T1} G_2 R_{x1} k_3 + C_{T2} G_1 R_{x1} k_3}{C_{T2}}\right) + (1+k_2) \left(1 + \frac{G_2 R_{x1}}{1+k_2}\right)\}$$
(26)

where $C_{T1} = C_1 + C_{z-3} + C_{y1}$, $C_{T2} = C_2 + C_{z-1} + C_{y2}$, $G_1 = (1/R_{z-3})/(1/R_{y1})$, $G_2 = (1/R_{z-1})/(1/R_{y2})$.

The parasitic impedance effects can be made negligible by satisfying the following condition: $C_{T1}G_2R_{x1}k_3 + C_{T2}G_1R_{x1}k_3 \neq 1$

$$\left. \begin{array}{c} \frac{G_2 K_{x1} k_3 + C_{T2} G_1 K_{x1} k_3}{C_{T2}} \ll 1\\ \frac{G_2 R_{x1}}{1 + k_2} \ll 1 \end{array} \right\}$$
(27)

The parasitic capacitance will affect the natural frequency and the quality factor that can be expressed respectively by $\omega_o = 1/\sqrt{C_{T1}C_{T2}R_{x1}R_{x2}}$ and $Q = (1+k)\sqrt{C_{T1}R_{x1}/C_{T2}R_{x2}}$, where $k_2 = k_3 = k$.

Considering the proposed shadow filters in Figure 5b by including the CCCII with the parasitic components in Figure 6, the denominator of all filtering functions is given by

$$D(s) = \{s^2 C_{T1} C_{T2} R_{x1} R_{x2} + s C_{T2} R_{x2} \left((1 - k_1) + \frac{C_{T1} G_2 R_{x1} + C_{T2} G_1 R_{x1}}{C_{T2}} \right) + (1 - k_2) \left(1 + \frac{G_1 G_2 R_{x1} R_{x2} + G_2 R_{x2} - G_2 R_{x2} k_1}{1 - k_2} \right) \}$$
(28)

The parasitic impedance effects can be made negligible by satisfying the following condition:

$$\left. \begin{array}{c} \frac{C_{T1}G_2R_{x1} + C_{T2}G_1R_{x1}}{C_{T2}} \ll 1\\ \frac{G_1G_2R_{x1}R_{x2} + G_2R_{x2} - G_2R_{x2}k_1}{1 - k_2} \ll 1 \end{array} \right\}$$
(29)

The parasitic capacitance will affect the natural frequency and the quality factor that can be expressed, respectively, by $\omega_o = \sqrt{(1-k_2)/C_{T1}C_{T2}R_{x1}R_{x2}}$ and $Q = (\sqrt{1-k_2}/(1-k_1))\sqrt{C_{T1}R_{x1}/C_{T2}R_{x2}}$.

The parasitic impedances of CCCIIs that affect the parameters ω_0 and Q of the proposed shadow filters in Figures 4b and 5b can be absorbed by choosing $C_1 >> C_{z-3} + C_{y1}$, $C_2 >> C_{z-1} + C_{y2}$, $R_{x1} << 1/G_1$, $R_{x2} << 1/G_2$.

3. Simulation Results

The proposed current-mode shadow filters were simulated using SPICE. The CCCII in Figure 2 was designed with the transistor model parameters of AT&T's ALA400 CBIC-R process [35]. The DC supply voltage was ± 2.5 V. The bias currents I_{bi} were fixed to 25 μ A and the bias current I_{ai} was used to control the current gain k_i (i = 1, 2, 3). The simulated performances of the CCCII with controlled current gain used in this paper are given in [36]. The capacitors C₁ and C₂ were 30 nF.

The first proposed filter in Figure 4b was simulated and the theoretical value was added for comparison. The first simulation was performed with A = 0 ($k_2 = k_3 = 0$), by setting the bias currents $I_{a2} = I_{a3} = 0 \mu A$ and the bias currents $I_{set1} = I_{set2} = I_{set3} = 25 \mu A$. This setting resulted in natural frequency (f_0) of 10.2 kHz and the quality factor (Q) of 1. Figure 7 shows the magnitude frequency responses of the LP, HP, BP, and BS filters and Figure 8 shows the magnitude and phase frequency responses of the AP filters. The simulated natural frequency was 10 kHz and was different from the theoretical value by 1.96%. The bandwidth of the filter was approximately 9 MHz.



Figure 7. Simulated magnitude frequency responses of the LP, HP, BP, and BS filters of the first current shadow filter in Figure 4b without modification of the natural frequency and the quality factor (sim = simulation, the = theoretical).



Figure 8. Simulated magnitude and phase frequency responses of the AP filter of the first currentmode shadow filter in Figure 4b without modification of the natural frequency and the quality factor (sim = simulation, the = theoretical).

Figure 9 shows the magnitude frequency response of the BP filter for different bias currents I_{set1} and I_{set2} of 5 μ A, 15 μ A, 50 μ A, and 100 μ A. The obtained natural frequencies were 1.97 kHz, 5.96 kHz, 19.99 kHz, and 40.22 kHz, respectively. The results of simulations were in close agreement with the theoretical values.



Figure 9. Simulated magnitude frequency responses of the BP filter of the first current-mode shadow filter in Figure 4b with modification of the natural frequency via the bias currents I_{set1} and I_{set2} ($I_{set1} = I_{set2} = I_{set}$) and setting the quality factor (Q) to 1 (Q = 1).

Figure 10a–d show the magnitude frequency responses of the LP, HP, BP, and BS filters, respectively, when the quality factor (Q) was changed by k (k = $k_2 = k_3$) as Q = 1 ($I_{a1,2} = 0 \mu A$), Q = 2 ($I_{a1,2} = 25 \mu A$), Q = 3 ($I_{a1,2} = 50 \mu A$), Q = 4 ($I_{a1,2} = 75 \mu A$), and Q = 5 ($I_{a1,2} = 100 \mu A$) while the bias currents I_{set1} , I_{set2} , and I_{set3} were set to 25 μA . Figure 11a,b show, respectively, the magnitude and phase frequency responses of the AP filter. Figures 10 and 11 are used to confirm that the shadow filter in Figure 4 can modify the quality factor by the gain k (or A).



Figure 10. Simulated magnitude frequency responses of the first current-mode shadow filter in Figure 4b, setting the quality factor by the amplifier k for: (**a**) LP, (**b**) HP, (**c**) BP, and (**d**) BS.

The second proposed current-mode filter in Figure 5b was simulated and compared with the theory. The first simulation was performed with $A_2 = 0$ ($k_2 = 0$), by setting the bias currents $I_{a2} = 0 \ \mu A$ and the bias currents $I_{set1} = I_{set2} = I_{set3} = 25 \ \mu A$ while the bias current I_{a1} was used to control the quality factor (Q) as Q = 1 ($I_{a1} = 0 \ \mu A$, $k_1 = 0$), Q = 3 ($I_{a1} = 16.7 \ \mu A$, $k_1 = 0.67$), Q = 5 ($I_{a1} = 20 \ \mu A$, $k_1 = 0.8$), Q = 7 ($I_{a1} = 21.5 \ \mu A$, $k_1 = 0.86$), and Q = 9 ($I_{a1} = 22.2 \ \mu A$, $k_1 = 0.88$). Figure 12a–d show the magnitude frequency responses of the LP, HP, BP, and BS filters and Figure 13a,b show, respectively, the magnitude and phase frequency responses of AP filter.



Figure 11. Simulated frequency responses of AP filter of the first current-mode shadow filter in Figure 4b, setting the quality factor by the amplifier k; (**a**) magnitude response and (**b**) phase response.



Figure 12. Simulated magnitude frequency responses of the second current-mode shadow filter in Figure 4b, setting the quality factor by the amplifier k_1 with $k_2 = 0$ for: (a) LP, (b) HP, (c) BP, (d) BS.



Figure 13. Simulated frequency responses of the AP filter of the second current-mode shadow filter in Figure 4b, setting the quality factor by the amplifier k_1 with $k_2 = 0$; (**a**) magnitude response and (**b**) phase response.

The second proposed shadow filter was simulated when the natural frequency was varied by k_2 (A₂) and k_1 (A₁) was used for constant Q = 1, and the bias currents $I_{set1} = I_{set2} = I_{set3} = 25 \ \mu$ A. Figure 14a–d show the magnitude frequency responses of the LP, HP, BP, and BS filters for $f_0 = 9.37$ kHz ($k_1 = 0.05$ ($I_{a1} = 1.25 \ \mu$ A), $k_2 = 0.1$ ($I_{a2} = 2.5 \ \mu$ A)), $f_0 = 8.13$ kHz ($k_1 = 0.16$ ($I_{a1} = 4 \ \mu$ A), $k_2 = 0.3$ ($I_{a2} = 7.5 \ \mu$ A)), $f_0 = 6.69$ kHz ($k_1 = 0.29$ ($I_{a1} = 7.25 \ \mu$ A), $k_2 = 0.5$ ($I_{a2} = 12.5 \ \mu$ A)), $f_0 = 4.84$ kHz ($k_1 = 0.45$ ($I_{a1} = 11.25 \ \mu$ A), $k_2 = 0.7$ ($I_{a2} = 17.5 \ \mu$ A)), and $f_0 = 2.93$ kHz ($k_1 = 0.68$ ($I_{a1} = 17 \ \mu$ A), $k_2 = 0.1$ ($I_{a2} = 22.5 \ \mu$ A)). Figure 15a,b show, respectively, the magnitude and phase frequency responses of the AP filter.



Figure 14. Cont.



Figure 14. Simulated magnitude frequency responses of the second current-mode shadow filter in Figure 4b, setting the natural frequency by k_2 , while k_1 is used to adjust Q = 1 for: (a) LP, (b) HP, (c) BP, (d) BS.



Figure 15. Simulated frequency responses of AP filter of the second current-mode shadow filter in Figure 4b, setting the natural frequency by k_2 , while k_1 is used to adjust Q = 1; (a) magnitude response and (b) phase response.

Figures 12–15 are used to confirm that the quality factor and the natural frequency of the shadow filter in Figure 5 can be modified independently by k_1 (or A_1) and k_2 (or A_2), respectively.

To investigate the linearity of the proposed shadow filter in Figure 4b, this filter was simulated with Q = 1 ($k_2 = k_3 = 0$, $I_{a2} = I_{a3} = 0 \mu A$), where the amplifier A was not active. Figure 16a shows the input and output waveforms of the LP filter for the frequency of 1 kHz, amplitude of 100 μ Ap-p, and total harmonic distortion (THD) of 0.937%. Figure 16b shows the simulated THD for the frequency of 1 kHz with different input amplitudes. Figure 16c shows the simulated third intermodulation distortion (IMD3) of the BP filter with a two-tone test, with two closely spaced tones $f_1 = 9$ kHz and $f_2 = 11$ kHz. The IMD3 was less than 1.55% for input amplitude up to 30 μ Ap-p.



Figure 16. Simulated distortion of first proposed current-mode shadow filter: (**a**) the transient response of the LP filter with THD less than 0.937% for $I_{in} = 100 \ \mu A_{p-p}$, (**b**) THD of the LP filter with different amplitude of I_{in} , and (**c**) IMD3 of the BP filter.

With the condition of Q = 1 and $f_c = 10$ kHz, the proposed current-mode shadow filter in Figure 4b was simulated to investigate the impact of process variations by varying beta (β) in BJT by 10% (LOT tolerance), voltage by varying the supply voltage by $\pm 10\%$, and temperature (PVT) corners by varying the temperature from -20 to 85 °C. Figure 17a–c show the simulated magnitude frequency responses of the LP, HP, BP, BS, and AP filters for process, voltage, and temperature (PVT) corners, respectively. It can be noted that the



natural frequency was affected by the temperature variations. From our investigation, for the temperatures of -20 °C and 85 °C, the natural frequencies were, respectively, 11.09 kHz and 8.81 kHz. Thus, the natural frequency was varied by about ± 1.04 kHz.

Figure 17. Simulated magnitude responses of the proposed current-mode shadow filter: (**a**) process corner, (**b**) voltage corner, and (**c**) temperature corner.

The BP response was simulated by setting 5% tolerances of the capacitor C_1 and C_2 at the cut-off frequency of 10 kHz and 200 Gaussian distribution runs. Figure 18 shows the derived histogram of the center frequency. The standard deviation (σ) of f_0 was 0.317 kHz and the maximum and minimum values of f_0 were, respectively, 10.805 kHz and 9.231 kHz.

The proposed current-mode shadow filters were compared with previous shadow filters in Table 1. The voltage-mode shadow filters in [15,22], the current-mode shadow filters in [27,28,30], and the multi-mode shadow filters in [34] were selected for comparison. Compared with [22,27,28], the proposed filter can provide five filtering functions of LP, HP, BP, BS, and AP filters. Compared with [15,30], the proposed filter does not possess a buffer circuit at input or output terminals. Compared with [15,34], the proposed filter has no resistors and has a simpler structure. As can be seen, the proposed filters have the following features which the others do not: they offer the highest number of responses without the need for a buffer circuit at the input and output, have no resistors, all capacitors are grounded, and they have the possibility of electronic tuning of the natural frequency and quality factor.



Figure 18. The histogram of the center frequency of the BP filter with 200 runs of MC analysis.

Factor	Proposed	[15]	[22]	[27]	[28]	[30]	[34]
Number of active devices	3 CCCII	3 VDDDA	4 DDTA	7 CDTA	4 OFCC	4 CDCTA, 1 CCII	2 DCCCTA
Realization	BJT process (ALA400 CBIC-R)	0.18 μm CMOS structure & commercial IC	0.18 μm CMOS structure	0.18 μm CMOS structure	0.15 μm CMOS structure & commercial IC	0.18 μm CMOS structure & commercial IC	0.18 μm CMOS structure
Number capacitors	2 C	2C, 1 R	2 C, 3 R	2 C	2 C, 5 R	2 C	2 C, 2 R
Type of filter	SIMO	SIMO	MISO	SIMO	SIMO	MIMO	SIMO
Operation mode	СМ	VM	VM	СМ	СМ	СМ	MM
Number of offered responses	5	5	4	1 (BP)	1 (BP)	5	5
No need of buffer circuit at input or output	Yes	No	Yes	Yes	Yes	No	Yes
All grounded capacitors	Yes	Yes	Yes	No	Yes	No	Yes
Electronic control	Yes	Yes	Yes	Yes	Yes	Yes	Yes
Technique to control Q and ω_0	CG	EG	EG	EG	EG	EG	EG

 Table 1. Comparison of the proposed design with previous works.

Factor	Proposed	[15]	[22]	[27]	[28]	[30]	[34]
Simulated power supply (V)	±2.5	±0.9	0.5	± 0.9	±1.5	±1.25	±1.7
Simulated power dissipation (mW)	9.9	-	0.000873	8.53	_	2.23	2.5
Total harmonic distortion (%)	0.937@100µA _{pp}	1@280mV _{pp}	2@60mV _{pp}	<5@100µA _{pp}	-	<1@600µA _{pp}	<1@200µA _{pp}
Verification of result	Sim/Exp	Sim/Exp	Exp	Sim	Sim/Exp	Sim/Exp	Sim/Exp

Table 1. Cont.

Note: DCCCTA = differential current conveyor cascaded transconductance amplifier, MM = multi-mode, DDTA = differential difference transconductance amplifier, CG = current gain, EG = external gain (i.e., $g_m R$, R_1/R_2 , and g_{m1}/g_{m2}).

4. Experimental Results

To confirm the functionality of the proposed shadow filters, an experimental setup of CCCII was designed using commercially available 2N3904 (NPN) and 2N3906 (PNP) transistors with supply voltage of ± 2.5 V. Figure 19 shows the experimental setup for the current-mode shadow filter. Passive capacitors were chosen as $C_1 = C_2 = 330$ nF and passive resistors 10 k Ω were used for voltage-to-current (V-I) converter as input and current-to-voltage (I-V) converter as output. The resistor that was connected in series with terminal I_{in} works as a V-I converter to convert the voltage signal from the function generator to the current signal I_{in} and the grounded resistors that were connected to terminals I_{LP}, I_{HP}, I_{BP}, I_{BS}, and I_{AP} were used as I-V converter to convert current signals to voltage signals. The input and output waveforms ware measured using a KEYSIGHT DSOX1204G oscilloscope; the input signal was also provided by this oscilloscope.



Figure 19. Experimental setup for proposed shadow filters.

The experimental frequency responses of the shadow filter in Figure 4b without modification of the natural frequency and the quality factor (A = 0, Q = 1) of (a) LP, (b) HP, (c) BP, (d) BS, and (e) AP are shown in Figure 20. Figure 21 shows the experimental

frequency responses of the shadow filter in Figure 4b upon setting the quality factor of the amplifier A \approx 3 of (a) LP, (b) HP, (c) BP, (d) BS, (e) AP.

Figure 22 shows the experimental frequency responses of the second shadow filter in Figure 5b, setting the quality factor by the amplifier k_1 with $k_2 = 0$ for: (a) LP, (b) HP, (c) BP, (d) BS. Figure 23 shows the experimental frequency responses of the second shadow filter in Figure 5b, setting the natural frequency by k_2 , while k_1 is used to adjust Q for (a) LP, (b) HP, (c) BP, (d) BS, (e) AP.



Figure 20. Experimental frequency responses of the first shadow filter in Figure 4b without modification of the natural frequency and the quality factor (A = 0, Q = 1) of (**a**) LP, (**b**) HP, (**c**) BP, (**d**) BS, and (**e**) AP.



Figure 21. Cont.



Figure 21. Experimental frequency responses of the first shadow filter in Figure 4b, setting the quality factor by the amplifier A \approx 3 of (a) LP, (b) HP, (c) BP, (d) BS, (e) AP.



Figure 22. Experimental frequency responses of the second current-mode shadow filter in Figure 5b setting the quality factor by the amplifier k_1 with $k_2 = 0$ for: (a) LP, (b) HP, (c) BP, (d) BS, and (e) AP.





Figure 23. Experimental frequency responses of the second shadow filter in Figure 5b, setting the natural frequency by k_2 , while k_1 is used to adjust Q for: (a) LP, (b) HP, (c) BP, (d) BS, (e) AP.

5. Conclusions

This paper proposes two current-mode shadow filters using CCCIIs with controlled current gains. The circuits employ three CCCIIs with controlled current gains and two grounded capacitors. The proposed architecture can realize LP, HP, BP, BS, and AP filters in the same topology. The current gains of CCCIIs can be used to modify the natural frequency and the quality factor of all filtering functions. The proposed shadow filters have the advantages of low-input and high-output impedances and low circuit complexity; they do not require passive resistors; they are suitable for integrated circuits by using grounded capacitors; and they have electronic tuning capability. To show the workability and performance of the proposed filters, SPICE simulation was performed. The simulated results were in agreement with the theoretical values and the experimental results confirm the functionality and the performance of the proposed filters.

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