High-speed Regular Expression Matching with Pipelined Memory-based Automata



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Introduction

Pattern matching based on regular expressions (REs) is a widely used operation in the domain of computer networks. It is a computationally intensive operation that is not suitable for sequential processing. It is used for DPI (deep packet inspection) techniques, which are used for network security monitoring and threat detection in IDS/IPS (intrusion detection/prevention systems) applications. Typical example is open-source software like Snort, Suricata, and Bro.

Another use case is application-level load balancing. Required throughput for current computer networks is 10 Gbps, moving on to 40 Gbps and 100 Gbps and it will be 400 Gbps soon. FPGAs (field-programmable gate array) are used to leverage their massive parallelism and programmability in order to accelerate the operation of pattern matching.

Throughput	Data bus width	Symbols
10 Gbps	64 b	8
40 Gbps	256 b	32
100 Gbps	512 b	64
400 Gbps	2048 b	256

Problem

Current pattern matching architectures do not scale above 10 Gbps. The techniques m*ultistriding* [1, 2] and *spatial stacking* [3, 4] modify the original automaton to process multiple input symbols with a single transition. The frequency of corresponding circuit decreases with increasing number of simultaneously processed input symbols as shown in the following table.

Architecture	Clock cycle	Frequency	Throughput
Multi-striding [1] (FPGA)	4 symbols	133 MHz	4 Gbps
Multi-striding [1] (ASIC)	4 symbols	500 MHz	16 Gbps
Multi-striding [2]	2 symbols	436.7 MHz	7 Gbps
Spatial stacking [3]	8 symbols	160.9 MHz	10.3 Gbps
Spatial stacking [4]	4 symbols	N/A	7.5 Gbps

Table 1: Data bus width for parallel processing @ 200 MHz

Table 2: Parameters of multi-striding and spatial stacking techniques

Delayed Input DFAs

Delayed Input DFA (D2FA) technique was introduced in [5]. It modifies an original DFA (deterministic finite automaton) by replacing multiple standard transitions with a *default*

transition. The algorithm can be applied iteratively to further reduce overall number of transitions. The number of iterations is called the *radius* of a D²FA. As a result, more than one transition can be used in order to accept a single input symbol. Effectively, the throughput of processing input characters is reduced. We carried out a research on how the throughput is reduced in real cases.



Analysis of D²FA



Figure 2: Reduction in the number of transition with D^2FA technique



Architecture and Input Data Processing

The architecture uses parallel *pipelined automata* concept [6]. Instead of distributing data among multiple independent matching engines (MEs), which would require complex distribution logic and utilize a lot of chip's resources, state is passed between adjacent matching engines. An example of packet processing is shown on the figures below. The state from the matching engine ME⁰, which processes the first part of the packet P1, is passed to the adjacent matching engine ME¹, which processes the second part of the packet P1. The processing of the packet P2 begins immediately with the processing of the packet P1 since corresponding matching engine ME² is not occupied.



Matching Engine

Matching engines use a pair of D²FAs to process input symbols. D²FA₀ is used to process standard transitions and D²FA₁ to process default transitions. A single transition table is used for both automata since dual-port feature of FPGA block memories is used. FIFO_{standard} is used to buffer standard transitions in case the following matching engine is not ready to process another input symbol. FIFO_{default} is used to buffer default transitions in order to accept input symbols.

Since there are two D²FAs in a ME, performing one default transition for each input symbol does not cause any delay in processing. In such case, neither $FIFO_{standard}$ nor $FIFO_{default}$ would be necessary. The FIFOs are present for cases when D²FA radius is greater than one. The



Figure 10: Architecture of a matching engine

fullness of FIFOs depends on the data that are being processed. The capacity of the FIFOs depends on the frequency of using default transitions. The greater the D²FA radius is, the greater the probability of using a default transition is. It is necessary to find a trade-off between the degree of reduction of the transition table and frequency of using default transitions.

Conclusion

The research addresses insufficient processing performance and flexibility of current architectures for pattern matching based on regular expressions. Resource utilization of the

References

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proposed architecture scales linearly with the width of input data bus and frequency remains the same. It achieves the throughput of 100 Gbps and 400 Gbps on current FPGA chips, Xilinx Virtex-7 and Xilinx Virtex UltraSCALE+, respectively. The use of memory-based automata brings the possibility to change the set of regular expressions without chip reconfiguration. Delayed Input DFAs significantly reduce the size of transition tables.

Resource utilization for two configurations is shown in the table below. They use a transition table with 8192 items. The width of items stored in $FIFO_{standard}$ is 13 bits (state) and in $FIFO_{default}$ 13 bits (state) + 8 bits (input symbol). The capacity of both FIFOs is three items.

Component	Throughput	BRAMs	LUTs	FFs
Single ME	N/A	9	201	124
64 MEs	100 Gbps	576	12 864	7936
256 MEs	400 Gbps	2304	51 456	31 744
Table 2. Desource u	tilization for cample config	urations		

 Table 3: Resource utilization for sample configurations

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